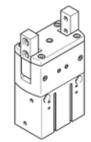
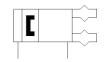
radial gripper HGRT-40-A Part number: 563912



Data sheet

Feature	Value
Size	40
Max. replacement accuracy	<= 0.2 mm
Max. angular gripper jaw backlash ax,ay	<= 0.1 deg
Max. opening angle	180 deg
Rotationally symmetrical	<= 0.2 mm
Repetition accuracy, gripper	<= 0.02 mm
Number of gripper fingers	2
Assembly position	Any
Mode of operation	double-acting
Gripper function	radial
Design structure	guided motion sequence
Position detection	For proximity sensor
	For inductive sensors
Operating pressure	3 8 bar
Max. operating frequency of gripper	<= 2 Hz
Min. opening time at 6 bar	283 ms
Min. closing time at 6 bar	320 ms
Operating medium	Compressed air in accordance with ISO8573-1:2010 [7:4:4]
Note on operating and pilot medium	Lubricated operation possible (subsequently required for further operation)
Corrosion resistance classification CRC	1 - Low corrosion stress
Ambient temperature	5 60 °C
Total gripping torque at 6 bar, opening	3,892 Ncm
Total gripping torque at 6 bar, closing	3,526 Ncm
Mass moment of inertia	13.87 kgcm2
Max. force on gripper jaw Fz static	400 N
Max. torque at gripper My static	17.5 Nm
Max. torque at gripper Mz static	1.6 Nm
Lubrication interval for guide components	10 Mio SP
Product weight	1,580 g
Mounting type	Internal thread and centring sleeve
Pneumatic connection	G1/8
Materials note	Free of copper and PTFE
	Conforms to RoHS
Material housing	Aluminium
	Smooth anodised
Material gripper jaws	Steel
	Hardened



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