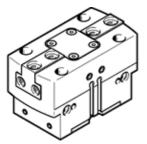
parallel gripper HGPT-35-A-B Part number: 560210

sturdy.



Data sheet

Feature	Value
Size	35
Stroke per gripper jaw	8 mm
Max. replacement accuracy	<= 0.2 mm
Max. angular gripper jaw backlash ax,ay	<= 0.1 deg
Max. gripper jaw backlash Sz	<= 0.02 mm
Rotationally symmetrical	<= 0.2 mm
Repetition accuracy, gripper	<= 0.05 mm
Number of gripper fingers	2
Assembly position	Any
Mode of operation	double-acting
Gripper function	Parallel
Design structure	Inclined plane
	guided motion sequence
Position detection	For proximity sensor
Total force at 6 bar, opening	490 N
Total force at 6 bar, closing	458 N
Operating pressure	3 8 bar
Operating pressure, sealing air	0 0.5 bar
Max. operating frequency of gripper	<= 3 Hz
Min. opening time at 6 bar	36 ms
Min. closing time at 6 bar	67 ms
Operating medium	Compressed air in accordance with ISO8573-1:2010 [7:4:4]
Note on operating and pilot medium	Lubricated operation possible (subsequently required for further operation)
Corrosion resistance classification CRC	2 - Moderate corrosion stress
Protection class	IP40
Ambient temperature	5 60 °C
Gripping force per gripper jaw at 6 bar, opening	245 N
Gripping force per gripper jaw at 6 bar, closing	229 N
Mass moment of inertia	2.807 kgcm2
Max. force on gripper jaw Fz static	1,800 N
Max. torque at gripper Mx static	80 Nm
Max. torque at gripper My static	60 Nm
Max. torque at gripper Mz static	50 Nm
Lubrication interval for guide components	5 Mio SP
Max. mass per external gripper finger	180 g
Product weight	490 g
Mounting type	Internal thread and centring sleeve
	With through-hole and centring sleeve
	With through-hole and dowel pin
	With internal thread and dowel pin
	Optional
Pneumatic connection, sealing air	M5
Pneumatic connection	M5

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FESTO

Feature	Value
Materials note	Free of copper and PTFE
	Conforms to RoHS
Material cover cap	High alloy steel, non-corrosive
Material housing	Aluminium
	Anodised
Material gripper jaws	Steel
	Hardened