## parallel gripper HGPP-32-A-G2 Part number: 525666

Precise, for position sensing via hall effect sensor or inductive sensors. With gripping force retention when closing...-G2.

## **Data sheet**

Feature	Value
Size	32
Stroke per gripper jaw	12.5 mm
Max. replacement accuracy	0.1 mm
Repetition accuracy, gripper	<= 0.02 mm
Number of gripper fingers	2
Mode of operation	double-acting
Gripper function	Parallel
Gripper force back-up	On closing
Design structure	Rack and pinion
Position detection	For Hall sensors
	For inductive sensors
Operating pressure	5 8 bar
Max. operating frequency of gripper	4 Hz
Min. opening time at 6 bar	103 ms
Min. closing time at 6 bar	101 ms
Operating medium	Compressed air in accordance with ISO8573-1:2010 [7:4:4]
Note on operating and pilot medium	Lubricated operation possible (subsequently required for further
	operation)
Corrosion resistance classification CRC	2 - Moderate corrosion stress
Ambient temperature	5 60 °C
Max. force on gripper jaw Fz static	720 N
Max. torque at gripper Mx static	30 Nm
Max. torque at gripper My static	30 Nm
Max. torque at gripper Mz static	30 Nm
Max. mass per external gripper finger	300 g
Product weight	1,427 g
Mounting type	with internal (female) thread
Pneumatic connection	G1/8
Materials note	Free of copper and PTFE
Material cover cap	РОМ
Material housing	Wrought Aluminium alloy
	Hard anodised
Material gripper jaws	Wrought Aluminium alloy
	Nickel plated

**FESTO**