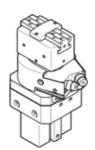
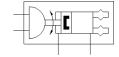
swivel/gripper unit HGDS-PP-20-P-A-B Part number: 1187961

FESTO

With flexible cushioning





Data sheet

Feature	Value
Size	20
Rotation angle adjustment range	0 210 deg
Stroke per gripper jaw	7 mm
Max. angular gripper jaw backlash ax,ay	0.1 deg
Max. gripper jaw backlash Sz	0.02 mm
Swivel angle	210 deg
Number of gripper fingers	2
Cushioning of swivel drive	P: Flexible cushioning rings/plates at both ends
Assembly position	Any
Fine adjustment of swivel drive	-6 deg
Mode of operation	double-acting
Gripper function	Parallel
Design structure	Swivel drive
Design structure	With parallel gripper and gripper drive
Position detection, gripper	with proximity sensor
Position detection, gripper Position detection, swivel drive	with proximity sensor with proximity sensor
	3 8 bar
Operating pressure Max. swivel frequency at 6 bar	2 Hz
Min. opening time at 6 bar	60 ms
Min. closing time at 6 bar	70 ms
Operating medium	Compressed air in accordance with ISO8573-1:2010 [7:4:4]
Note on operating and pilot medium	Lubricated operation possible (subsequently required for further operation)
Corrosion resistance classification CRC	2 - Moderate corrosion stress
Ambient temperature	5 60 °C
Gripping force per gripper jaw at 6 bar, opening	96 N
Total force at 6 bar, opening	192 N
Gripping force per gripper jaw at 6 bar, closing	84 N
Total force at 6 bar, closing	168 N
Max. force on gripper jaw Fz static	250 N
Max. torque at gripper Mx static	22 Nm
Max. torque at gripper My static	22 Nm
Max. torque at gripper Mz static	22 Nm
Theoretical torque at 6 bar	2.5 Nm
Max. mass per external gripper finger	100 g
Product weight	1,260 g
Mounting type	Internal thread and centring sleeve
	With through-hole and centring sleeve
	With dovetail slot
	Optional
Pneumatic connection	M5
Materials note	Conforms to RoHS
Material of drive shaft	Steel
Material cover	Aluminium
	POM
Material seals	NBR
Material housing	Wrought Aluminium alloy
Material gripper jaws	High alloy steel, non-corrosive